HITACHI

Mini-Excavator ZAXIS40U Specifications

Rated Engine Power

DIN 6271, net 29.3 kW (39.8 PS) SAE J1349, net 29.9 kW (40.1 hp)

Operating Weight (Rubber shoes) (Grouser shoes)
2-pillar canopy version 4 210 kg 4 350 kg
4-pillar canopy version 4 270 kg 4 410 kg
Cab version 4 330 kg 4 470 kg

Backhoe Buckets

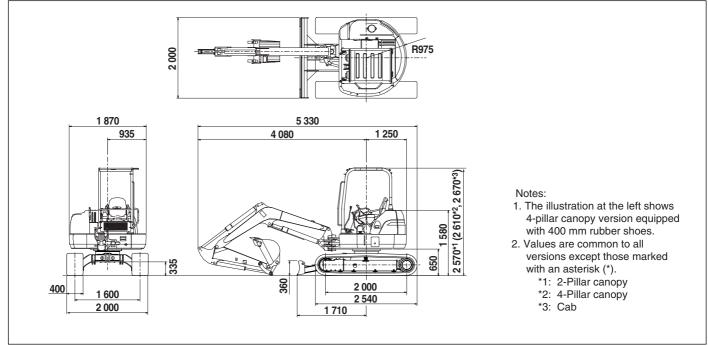
ISO 7451 0.10 – 0.17 m³

The 2- or 4-pillar canopy, or cab can be mounted on the upperstructure according to job needs and applicable regulations. The 4-pillar canopy and cab conform to TOPS (ISO 12117) and FOPS (ISO 10262, Level 1)* requirements.

* Cab requires optional top guard.

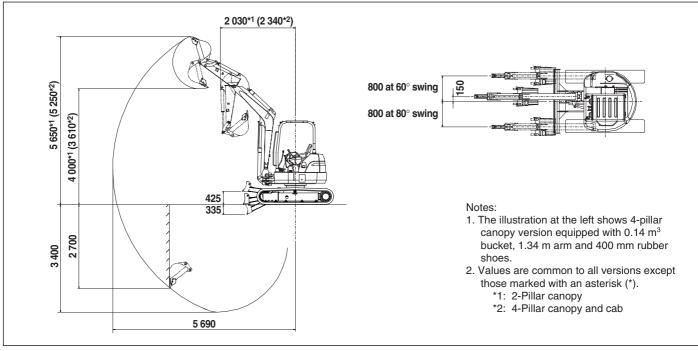
■ DIMENSIONS

Unit : mm



■ WORKING RANGES

Unit: mm







ENGINE

Model	Isuzu CC4LE2
Type	Water-cooled, 4-cycle, 4-cylinder
	direct injection type diesel engine
Rated power	29.3 kW (39.8 PS)
DIN 6271, net	at 2 200 min ⁻¹ (rpm)
Rated power	29.9 kW (40.1 hp)
SAE J1349, net	at 2 200 min ⁻¹ (rpm)
Maximum torque	145 N·m (14.8 kgf·m)
	at 1 600 min ⁻¹ (rpm)
Piston displacement	2.179 L
Bore and stroke	85 mm x 96 mm
Battery	1 x 12 V, 52 Ah



HYDRAULIC SYSTEM

The HHH system for job efficiency and smooth combined operations.

Main pump	One variable displacement axial
	piston pump
Maximum oil flow	110 L/min
Pilot pump	One gear pump
Maximum oil flow	11 0 L/min

Relief Valve Settings

Implement circuit	24.5 MPa (250 kgf/cm ²)
Swing circuit	19.6 MPa (200 kgf/cm ²)
Travel circuit	24.5 MPa (250 kgf/cm ²)
Pilot circuit	3.9 MPa (40 kgf/cm ²)

Hvdraulic Cvlinders

High-strength piston rods and tubes. Cylinder cushion mechanisms provided in boom raise, arm roll-in and roll-out circuits to absorb shocks at stroke ends.

Dimensions

No.	Bore	Rod dia.	Stroke
1	90 mm	55 mm	707 mm (696 mm)
. 1	80 mm	50 mm	702 mm
1	70 mm	40 mm	551 mm
. 1	100 mm	50 mm	575 mm
. 1	105 mm	50 mm	140 mm
	1 . 1 . 1	1 90 mm . 1 80 mm 1 70 mm . 1 100 mm	No. Bore Rod dia. 1 90 mm 55 mm 1 80 mm 50 mm 1 70 mm 40 mm .1 100 mm 50 mm .1 105 mm 50 mm

Note: The figure in () shows the stroke for 4-pillar canopy version and cab version.



CONTROLS

Hydraulic pilot control levers for all operations.



SWING MECHANISM

High-torque, axial piston motor with planetary reduction gear. Swing circle is single-row, shear-type ball bearing with induction-hardened internal gear. Internal gear and pinion are immersed in lubricant. Swing parking brake is springset/hydraulic-released disc type. Swing shockless valve built in swing motor absorbs shocks when stopping swing, ensuring smooth stops.

Swing speed...... 9.0 min⁻¹ (9.0 rpm)

UNDERCARRIAGE

Tracks

Tractor-type undercarriage. Welded track frame using carefully selected materials. Side frame welded to track frame.

Numbers of Rollers on Each Side

Upper roller1
Lower rollers4

Traction Device

Each track driven by a high-torque, 2-speed axial piston motor through planetary reduction gear, allowing counter-rotation of the tracks. Travel shockless relief valve built in travel motor absorbs shocks when stopping travel, ensuring smooth stops. Parking brake is spring-set / hydraulic-released disc type.

Travel speeds (rubber shoes)	High : 0 - 4.4 km/h
	Low : 0 - 2.2 km/h
Travel speeds (grouser shoes).	
	Low : 0 - 2.0 km/h
Gradeability	30 degrees (58%) continuous



WEIGHTS AND GROUND PRESSURE

Equipped with 2.73 m boom, 1.34 m arm and 0.14 m3 (PCSA heaped) bucket

	Operating weight	Ground pressure
2-Pillar canopy version	_	
400 mm rubber shoes	4 210 kg	24 kPa (0.24 kgf/cm ²)
400 mm grouser shoes	4 350 kg	25 kPa (0.25 kgf/cm ²)
4-Pillar canopy version	•	, ,
400 mm rubber shoes	4 270 kg	24 kPa (0.24 kgf/cm ²)
400 mm grouser shoes	4 410 kg	25 kPa (0.26 kgf/cm ²)
Cab version	•	, ,
400 mm rubber shoes	4 330 kg	24 kPa (0.25 kgf/cm ²)
400 mm grouser shoes	4 470 kg	25 kPa (0.26 kgf/cm ²)



FRONT-END ATTACHMENTS

Backhoe Buckets

ISO Width		dth	No. of		Use		
7451 capacity	Without side cutters	With side cutters	teeth	Weight	1.34 m Std. arm	1.69 m Long arm	
0.10 m ³	405 mm	450 mm	3	90 kg	Α	Α	
0.11 m ³	455 mm	500 mm	3	94 kg	Α	Α	
$0.13 m^3$	505 mm	550 mm	4	103 kg	Α	В	
0.14 m ³	555 mm	600 mm	4	108 kg	Α	С	
0.16 m ³	605 mm	650 mm	4	114 kg	С	С	
0.17 m ³	655 mm	700 mm	4	117 kg	С	С	
	Arm c		23.1 kN (2 360 kgf)	20.1 kN (2 050 kgf)			
	Bucke	et digging f	orce		32.2 kN (3 280 kgf)	

- A: General digging
- B: Light-duty digging
- C: Loading

Boom swing angle.....Left 60°, Right 80°



STANDARD EQUIPMENT

Notes: *1: For 4-pillar canopy and

cab versions

*2: For cab versions

Engine

Water-separator for engine fuel system

Hydraulic System

- Hydraulic pilot type control levers
- Pilot control shut-off levers
- · Anti-drift valve for front attachments
- Two-speed travel system
- Swing parking brake

Operator's Room

- Two work lights • Heater*2
- Windshield wiper*2
- Evacuation hammer*2
- Seat belt*1
- Utility box

Undercarriage

- 400 mm rubber shoes
- · Semi-long stay blade

Front Attachments

- 2.73 m boom
- 1.34 m arm
- 0.14 m3 hoe bucket
- Bucket clearance adjusting device
- O-ring type pin-seals for hoe bucket
- HN bushing

Zaxis40U

OPTIONAL EQUIPMENT

Engine

Auto-idling system

Hvdraulic System

- Hydraulic P.T.O. port
- Hydraulic piping for breaker
- Travel parking brake Swing motion alarm device with lamp
- Travel motion alarm device

Operator's Room

- Heater*2
- Air cooler*3 Seat belt*1
- Windshield washer*3 Notes: *1 : For 2-pillar canopy version
- *2 : For 2- and 4-pillar canopy Wrist rest
- 12V outlet
- versions *3 : For cab version • Air cleaner inner element
- FOPS top guard*3
- 2-way control lever pattern selector valve (Excavator/Backhoe loader)

Undercarriage

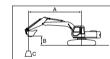
- 400 mm grouser shoes
- 400 mm triangle shoes
- 550 mm grouser shoes
- 400 mm pad crawler shoes
- Long stay blade

Front Attachments

- 1.69 m arm
- Backhoe buckets; see page 2.

Counterweight

Weight-added counterweight (270 kg added)



A: Load radius B: Load point height C: Lifting capacity

Bating over-side or 360 degrees Bating over-front

With dozer blade above ground

■ LIFTING CAPACITIES

(Equipped with 2-pillar canopy)

with dozer blade a	bove grou	ına			•••				3	Unit: 1 000 kg
				Load I	Maximum Reach					
	Load Point	3 m		4 m				5 m		
Conditions	Height		Ū		Ū		Ğ		Ğ	meter
	3 m	*0.96	*0.96	0.65	0.79			0.41	0.51	5.12
Arm: 1.34 m	2 m	1.01	1.26	0.62	0.77			0.36	0.45	5.42
Bucket: 0.14 m ³ ISO 7451	1 m	0.91	1.16	0.59	0.73	0.40	0.50	0.35	0.44	5.45
Rubber shoes: 400 mm	Ground	0.87	1.11	0.56	0.70	0.39	0.49	0.37	0.46	5.22
	– 1 m	0.87	1.11	0.55	0.69			0.45	0.56	4.66

With dozer blade on ground

		Load Radius						Maximum Reach		
Conditions	Load Point	3 m		4 m		5 m		waxiiiuiii neacii		
	Height		Ğ		Ů		Ğ		Ğ	meter
Arm: 1.34 m Bucket: 0.14 m ³ ISO 7451 Rubber shoes: 400 mm	3 m	*0.96	*0.96	0.65	*0.96			0.41	*0.68	5.12
	2 m	1.01	*1.39	0.62	*1.08			0.36	*0.69	5.42
	1 m	0.91	*1.99	0.59	*1.28	0.40	*1.01	0.35	*0.75	5.45
	Ground	0.87	*2.13	0.56	*1.40	0.39	*1.01	0.37	*0.86	5.22
	– 1 m	0.87	*1.93	0.55	*1.32			0.45	*0.88	4.66

Notes: 1. Rating are based on ISO 10567.

- 2. Lifting capacity does not exceed 75% of tipping load with the machine on firm, level ground or 87% full hydraulic capacity.
- 3. The load point is a hook (not standard equipment) located on the back of the bucket.
- 4. An asterisk mark (*) indicates load limited by hydraulic capacity.



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The Specifications include data that are not applicable to certain areas. Optional equipment may vary with territory specifications. Specifications are subject to change without notice.

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