# **HITACHI**

# Mini-Excavator ZAXIS30U Specifications

Rated Engine Power

DIN 6271, net 22.5 kW (30.6 PS) SAE J1349, net 23.0 kW (30.9 hp)

Operating Weight (Rubber shoes) (Grouser shoes)
2-Pillar canopy version 3 060 kg 3 140 kg
4-Pillar canopy version 3 120 kg 3 200 kg
Cab version 3 180 kg 3 260 kg

**Backhoe Buckets** 

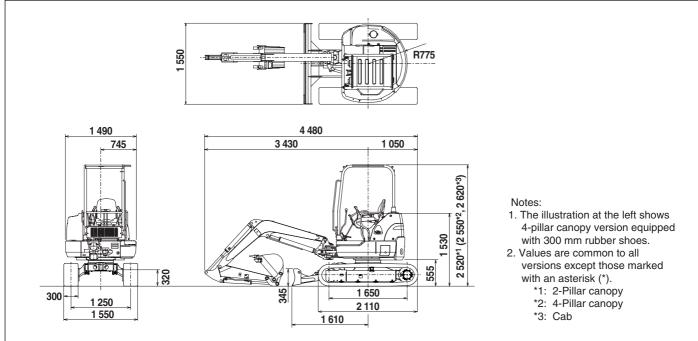
ISO 7451 0.055 - 0.13 m<sup>3</sup>

The 2- or 4-pillar canopy, or cab can be mounted on the upperstructure according to job needs and applicable regulations. The 4-pillar canopy and cab conform to TOPS (ISO 12117) and FOPS (ISO 10262, Level 1)\* requirements.

\* Cab requires optional top guard.

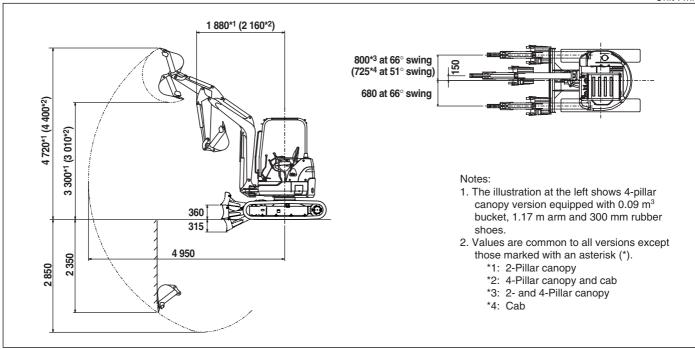
# **■ DIMENSIONS**

Unit : mm



## **■ WORKING RANGES**

Unit : mm







### **ENGINE**

	Isuzu AA-3LD2
Type	Water-cooled, 4-cycle, 3-cylinder
,,	direct injection type diesel engine
Rated power	22.5 kW (30.6 PS)
	at 2 450 min-1 (rpm)
Rated power	23.0 kW (30.9 hp)
SAE J1349, net	at 2 450 min <sup>-1</sup> (rpm)
Maximum torque	97 N·m (9.9 kgf·m)
·	at 1 800 min-1 (rpm)
Piston displacement	1.496 L
	83.1 mm x 92 mm
	1 x 12 V, 52 Ah



### HYDRAULIC SYSTEM

The Optimum Hyraulic System (OHS) uses three pumps for job efficiency and smooth combined operations.

Main pumps	Two variable displacement axial
	piston pumps
Maximum oil flow	2 x 40.8 L/min
	One gear pump
Maximum oil flow	26.8 L/min
Pilot pump	One gear pump
Maximum oil flow	

### Relief Valve Settings

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Implement circuit	24.5 MPa (250 kgf/cm <sup>2</sup> )
Swing circuit	13.7 MPa (140 kgf/cm <sup>2</sup> )
Travel circuit	
Pilot circuit	3.9 MPa (40 kgf/cm <sup>2</sup> )

### **Hvdraulic Cvlinders**

High-strength piston rods and tubes. Cylinder cushion mechanisms provided in boom raise, arm roll-in and roll-out circuits to absorb shocks at stroke ends.

### Dimensions

	INO.	Bore	Hod dia.	Stroke
Boom	1	75 mm	45 mm	569 mm (541 mm)
Arm	. 1	75 mm	45 mm	589 mm
Bucket	. 1	65 mm	40 mm	440 mm
Boom swing	. 1	85 mm	45 mm	517 mm
Blade	. 1	85 mm	45 mm	135 mm

No. Box Box State Order

Note: The figure in ( ) shows the stroke for 4-pillar canopy version and cab version.



### **CONTROLS**

Hydraulic pilot control levers for all operations.



### **SWING MECHANISM**

High-torque, axial piston motor with planetary reduction gear. Swing circle is single-row, shear-type ball bearing with induction-hardened internal gear. Internal gear and pinion are immersed in lubricant. Swing parking brake is springset/hydraulic-released disc type. Swing shockless valve built in swing motor absorbs shocks when stopping swing, ensuring smooth stops.

Swing speed	00,	min-1	(O O	rnm	١
Swing speed	9.U r	nın '	(9.0	rom	)

### **UNDERCARRIAGE**

### Tracks

Tractor-type undercarriage. Welded track frame using carefully selected materials. Side frame welded to track frame.

### Numbers of Rollers on Each Side

Upper roller1
Lower rollers4

### **Traction Device**

Each track driven by a high-torque, 2-speed axial piston motor through planetary reduction gear, allowing counter-rotation of the tracks. Travel shockless relief valve built in travel motor absorbs shocks when stopping travel, ensuring smooth stops. Parking brake is spring-set / hydraulic-released disc type.

Travel speeds (rubber shoes)	
Travel speeds (grouser shoes)	Low : 0 – 2.8 km/h
,	Low : $0 - 2.7 \text{ km/h}$
Gradeability	30 degrees (58%) continuous



### **WEIGHTS AND GROUND PRESSURE**

Equipped with 2.28 m boom, 1.17 m arm and 0.09 m3 (PCSA heaped) bucket

	Operating	Ground	
	weight	pressure	
2-Pillar canopy version			
300 mm rubber shoes	3 060 kg	28 kPa (0.28 kgf/cm <sup>2</sup>	)
300 mm grouser shoes.	. 3 140 kg	28 kPa (0.29 kgf/cm <sup>2</sup>	)
4-Pillar cab version	_		
300 mm rubber shoes	3 120 kg	28 kPa (0.29 kgf/cm <sup>2</sup>	)
300 mm grouser shoes.	. 3 200 kg	29 kPa (0.29 kgf/cm <sup>2</sup>	)
Cab version	_		
300 mm rubber shoes	3 180 kg	29 kPa (0.29 kgf/cm2	)
300 mm grouser shoes.	. 3 260 kg	29 kPa (0.30 kgf/cm <sup>2</sup>	)
•	U	, 0	1



### FRONT-END ATTACHMENTS

### Backhoe Buckets

ISO	Wic	dth	No. of		Use		
7451 capacity	Without side cutters	With side cutters	teeth	Weight	1.17 m Std. arm	1.47 m Long arm	
0.055 m <sup>3</sup>	300 mm	350 mm	3	61 kg	Α	Α	
0.065 m <sup>3</sup>	350 mm	400 mm	3	64 kg	Α	Α	
$0.08 \; m^3$	400 mm	450 mm	3	67 kg	Α	Α	
0.09 m <sup>3</sup>	450 mm	500 mm	4	71 kg	Α	В	
0.10 m <sup>3</sup>	500 mm	550 mm	4	74 kg	В	С	
0.11 m <sup>3</sup>	550 mm	600 mm	4	78 kg	С	С	
$0.13  \text{m}^3$	600 mm	650 mm	4	82 kg	С	D	
	Arm c	. 0,	14.7 kN (1 500 kgf)				
	Bucke	t digging fo	orce		27.5 kN (2 800 kgf)		

- A: General digging
- B: Light-duty digging
- C: Loading
- D: Not recommended

### Boom swing angle 2- and 4-pillar canopy versions.....Left 66°, Right 66° Cab version.....Left 66°. Right 51°



### STANDARD EQUIPMENT

### Engine

Water-separator for engine fuel system

### **Hvdraulic System**

- Hydraulic pilot type control levers for boom, arm, bucket and swing
- Mechanical linkage type control levers for travel, boom swing and blade
- Pilot control shut-off levers for boom, arm, bucket and swing
- · Anti-drift valve for front attachments
- Two-speed travel system Swing parking brake

# Operator's Room

- Two work lights
- Heater\*2
- Windshield wiper\*2
- Evacuation hammer\*2
- Seat belt\*1

### Notes: \*1: For 4-pillar canopy and cab versions

# \*2 : For cab versions

- Undercarriage
- 300 mm rubber shoes · Semi-long stay blade

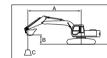
### Front Attachments

- 2.28 m boom
- 1.17 m arm
- 0.09 m3 hoe bucket
- Bucket clearance adjusting device
- O-ring type pin-seals for hoe bucket

**■ LIFTING CAPACITIES** 

(Equipped with 2-pillar canopy)

HN bushing



• Weight-added counterweight (270 kg added)

A: Load radius B: Load point height C: Lifting capacity

\*2 : For 2- and 4-pillar canopy

versions

\*3 : For cab version

### With dozer blade above ground

Rating over-side or 360 degrees Rating over-front Unit: 1 000 kg

		Load Radius						Maximum Reach		
0	Conditions Load Point Height	2 m		3 m		4 m		Maximum neach		
Conditions			Ш		Ů		ď		Ů	meter
Arm: 1.17 m Bucket: 0.09 m <sup>3</sup> ISO 7451 Rubber shoes: 300 mm	3 m			0.51	*0.57			0.27	0.35	4.24
	2 m			0.49	0.63	0.29	0.38	0.22	0.29	4.66
	1 m			0.45	0.58	0.28	0.36	0.20	0.27	4.75
	Ground			0.42	0.55	0.27	0.35	0.22	0.29	4.53
	– 1 m	0.81	1.11	0.41	0.55			0.28	0.37	3.91

### With dozer blade on ground

		Load Radius						Maximum Reach		
0	Load Point	2 m		3 m		4 m		waxiiiuili neacii		
Conditions	Height		Ü		Ū		Ü		Ğ	meter
Arm: 1.17 m Bucket: 0.09 m <sup>3</sup> ISO 7451 Rubber shoes: 300 mm	3 m			0.51	*0.57			0.27	*0.58	4.24
	2 m			0.49	*0.70	0.29	*0.64	0.22	*0.57	4.66
	1 m			0.45	*1.02	0.28	*0.72	0.20	*0.61	4.75
	Ground			0.42	*1.19	0.27	*0.78	0.22	*0.62	4.53
	– 1 m	0.81	*1.74	0.41	*1.10			0.28	*0.60	3.91

Notes: 1. Rating are based on ISO 10567.

- 2. Lifting capacity does not exceed 75% of tipping load with the machine on firm, level ground or 87% full hydraulic capacity.
- 3. The load point is a hook (not standard equipment) located on the back of the bucket.
- 4. An asterisk mark (\*) indicates load limited by hydraulic capacity.





**OPTIONAL EQUIPMENT** 

Windshield washer\*3 Notes: \*1 : For 2-pillar canopy version

Engine

Auto-idling system

Travel parking brake

Operator's Room

• Heater\*2

Air cooler\*3

Seat helt\*1

Wrist rest

• 12V outlet

Hydraulic piping for breaker

Travel motion alarm device

· Air cleaner inner element

• 300 mm grouser shoes

• 400 mm triangle shoes

• 400 mm grouser shoes

Front Attachments

• 1.47 m arm

Counterweight

• 300 mm pad crawler shoes

· Backhoe buckets; see page 2.

(Excavator/Backhoe loader)

FOPS top guard\*3

Undercarriage

Swing motion alarm device with lamp

• 2-way control lever pattern selector valve

**Hvdraulic System** Hydraulic P.T.O. port





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The Specifications include data that are not applicable to certain areas. Optional equipment may vary with territory specifications. Specifications are subject to change without notice.

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